



# $(t, i, f)$ -Neutrosophic Structures & $I$ -Neutrosophic Structures (Revisited)

Florentin Smarandache<sup>1</sup>

<sup>1</sup> University of New Mexico, 705 Gurley Ave., Gallup, NM 87301, USA. E-mail: smarand@unm.edu

**Abstract.** This paper is an improvement of our paper “ $(t, i, f)$ -Neutrosophic Structures” [1], where we introduced for the first time a new type of structures, called  $(t, i, f)$ -Neutrosophic Structures, presented from a neutrosophic logic perspective, and we showed particular cases of such structures in geometry and in algebra.

In any field of knowledge, each structure is composed from two parts: a space, and a set of axioms (or laws) acting (governing) on it. If the space, or at least one of its axioms (laws), has some indeterminacy of the form  $(t, i, f) \neq (1, 0, 0)$ , that structure is a  $(t, i, f)$ -Neutrosophic Structure.

The  $(t, i, f)$ -Neutrosophic Structures [based on the components  $t = \text{truth}$ ,  $i = \text{numerical indeterminacy}$ ,  $f = \text{falsehood}$ ] are different from the *Neutrosophic Algebraic*

*Structures* [based on neutrosophic numbers of the form  $a + bI$ , where  $I = \text{literal indeterminacy}$  and  $In = I$ ], that we rename as *I-Neutrosophic Algebraic Structures* (meaning algebraic structures based on indeterminacy “ $I$ ” only). But we can combine both and obtain the  $(t, i, f)$ -*I-Neutrosophic Algebraic Structures*, i.e. algebraic structures based on neutrosophic numbers of the form  $a+bI$ , but also having indeterminacy of the form  $(t, i, f) \neq (1, 0, 0)$  related to the structure space (elements which only partially belong to the space, or elements we know nothing if they belong to the space or not) or indeterminacy of the form  $(t, i, f) \neq (1, 0, 0)$  related to at least one axiom (or law) acting on the structure space. Then we extend them to *Refined  $(t, i, f)$ - Refined I-Neutrosophic Algebraic Structures*.

**Keywords:**  $(t, i, f)$ -neutrosophic structure, truth-indeterminacy-falsehood, neutrosophic axiom, indeterminacy, degree of indeterminacy, neutrosophic algebraic structures, neutrosophic groupoid, neutrosophic semigroup, neutrosophic group, neutrosophic linear algebras, neutrosophic bi-algebraic structures, neutrosophic  $N$ -algebraic,  $(t, i, f)$ -Neutrosophic Geometry

## 1 Classification of Indeterminacies

### 1.1 Numerical Indeterminacy

*Numerical Indeterminacy* (or *Degree of Indeterminacy*), which has the form  $(t, i, f) \neq (1, 0, 0)$ , where  $t, i, f$  are numbers, intervals, or subsets included in the unit interval  $[0, 1]$ , and it is the base for the  $(t, i, f)$ -Neutrosophic Structures.

### 1.1 Non-numerical Indeterminacy

*Non-numerical Indeterminacy* (or *Literal Indeterminacy*), which is the letter “ $I$ ” standing for unknown (non-determinate), such that  $I^2 = I$ , and used in the composition of the neutrosophic number  $N = a + bI$ , where  $a$  and  $b$  are real or complex numbers, and  $a$  is the determinate part of number  $N$ , while  $bI$  is the indeterminate part of  $N$ . The neutrosophic numbers are the base for the *I-Neutrosophic Structures*.

## 2 Neutrosophic Algebraic Structures [or $I$ -Neutrosophic Algebraic Structures]

A previous type of neutrosophic structures was introduced in algebra by W. B. Vasantha Kandasamy and Flor-

entin Smarandache [2-57], since 2003, and it was called Neutrosophic Algebraic Structures. Later on, more researchers joined the neutrosophic research, such as: Mumtaz Ali, Said Broumi, Jun Ye, A. A. Salama, Muhammad Shabir, K. Ilanthenral, Meena Kandasamy, H. Wang, Y.-Q. Zhang, R. Sunderraman, Andrew Schumann, Salah Osman, D. Rabounski, V. Christianto, Jiang Zhengjie, Tudor Paroiu, Stefan Vladutescu, Mirela Teodorescu, Daniela Gifu, Alina Tenescu, Fu Yuhua, Francisco Gallego Lupiañez, etc.

The neutrosophic algebraic structures are algebraic structures based on sets of neutrosophic numbers of the form  $N = a + bI$ , where  $a, b$  are real (or complex) numbers, and  $a$  is called the determinate part on  $N$  and  $bI$  is called the indeterminate part of  $N$ , with  $mI + nI = (m + n)I$ ,  $0 \cdot I = 0$ ,  $In = I$  for integer  $n \geq 1$ , and  $I / I = \text{undefined}$ .

When  $a, b$  are real numbers, then  $a + bI$  is called a neutrosophic real number. While if at least one of  $a, b$  is a complex number, then  $a + bI$  is called a neutrosophic complex number.

We may say “literal indeterminacy” for “ $I$ ” from  $a+bI$ , and “numerical indeterminacy” for “ $i$ ” from  $(t, i, f)$  in order to distinguish them.

The neutrosophic algebraic structures studied by Vasantha-Smarandache in the period 2003-2015 are: neutrosophic groupoid, neutrosophic semigroup, neutrosophic group, neutrosophic ring, neutrosophic field, neutrosophic vector space, neutrosophic linear algebras etc., which later (between 2006-2011) were generalized by the same researchers to neutrosophic bi-algebraic structures, and more general to neutrosophic N-algebraic structures.

Afterwards, the neutrosophic structures were further extended to neutrosophic soft algebraic structures by Florentin Smarandache, Mumtaz Ali, Muhammad Shabir, and Munazza Naz in 2013-2014.

In 2015 Smarandache refined the literal indeterminacy  $I$  into different types of literal indeterminacies (depending on the problem to solve) such as  $I_1, I_2, \dots, I_p$  with integer  $p \geq 1$ , and obtained the *refined neutrosophic numbers* of the form  $N_p = a + b_1I_1 + b_2I_2 + \dots + b_pI_p$  where  $a, b_1, b_2, \dots, b_p$  are real or complex numbers, and  $a$  is called the *determinate part* of  $N_p$ , while for each  $k \in \{1, 2, \dots, p\}$   $b_kI_k$  is called the *k-th indeterminate part* of  $N_p$ ,

and for each  $k \in \{1, 2, \dots, p\}$ , one similarly has:

$mI_k + nI_k = (m + n)I_k, 0 \cdot I_k = 0, I_k^n = I_k$  for integer  $n \geq 1$ , and  $I_k/I_k =$  undefined.

The relationships and operations between  $I_j$  and  $I_k$ , for  $j \neq k$ , depend on each particular problem we need to solve.

Then consequently Smarandache [2015] extended the neutrosophic algebraic structures to *Refined Neutrosophic Algebraic Structures* [or *Refined I-Neutrosophic Algebraic Structures*], which are algebraic structures based on the sets of the refined neutrosophic numbers  $a + b_1I_1 + b_2I_2 + \dots + b_pI_p$ .

### 3 (t, i, f)-Neutrosophic Structures

We now introduce for the first time another type of neutrosophic structures.

These structures, in any field of knowledge, are considered from a *neutrosophic logic point of view*, i.e. from the truth-indeterminacy-falsehood  $(t, i, f)$  values. In neutrosophic logic every proposition has a degree of truth  $(t)$ , a degree of indeterminacy  $(i)$ , and a degree of falsehood  $(f)$ , where  $t, i, f$  are standard or non-standard subsets of the non-standard unit interval  $]0, 1^+[$ . In technical applications  $t, i$ , and  $f$  are only standard subsets of the standard unit interval  $[0, 1]$  with:

$$0 \leq \sup(T) + \sup(I) + \sup(F) \leq 3^+$$

where  $\sup(X)$  means supremum of the subset  $X$ .

In general, each structure is composed from: a *space*, endowed with a *set of axioms* (or *laws*) acting (governing) on it. If the space, or at least one of its axioms, has some numerical indeterminacy of the form  $(t, i, f) \neq (1, 0, 0)$ , we consider it as a *(t, i, f)-Neutrosophic Structure*.

Indeterminacy with respect to the space is referred to some elements that partially belong [i.e. with a neutrosophic value  $(t, i, f) \neq (1, 0, 0)$ ] to the space, or their appurtenance to the space is unknown.

An axiom (or law) which deals with numerical indeterminacy is called *neutrosophic axiom* (or *law*).

We introduce these new structures because in the real world we do not always know exactly or completely the space we work in; and because the axioms (or laws) are not always well defined on this space, or may have indeterminacies when applying them.

### 4 Refined (t, i, f)-Neutrosophic Structures [or (t<sub>j</sub>, i<sub>k</sub>, f<sub>l</sub>)-Neutrosophic Structures]

In 2013 Smarandache [76] refined the numerical neutrosophic components  $(t, i, f)$  into  $(t_1, t_2, \dots, t_m; i_1, i_2, \dots, i_p; f_1, f_2, \dots, f_r)$ , where  $m, p, r$  are integers  $\geq 1$ .

Consequently, we now [2015] extend the  $(t, i, f)$ -Neutrosophic Structures to  $(t_1, t_2, \dots, t_m; i_1, i_2, \dots, i_p; f_1, f_2, \dots, f_r)$ -Neutrosophic Structures, that we called *Refined (t, i, f)-Neutrosophic Structures* [or  $(t_j, i_k, f_l)$ -Neutrosophic Structures].

These are structures whose elements have a refined neutrosophic value of the form  $(t_1, t_2, \dots, t_m; i_1, i_2, \dots, i_p; f_1, f_2, \dots, f_r)$  or the space has some indeterminacy of this form.

### 5 (t, i, f)-I-Neutrosophic Algebraic Structures

The  $(t, i, f)$ -Neutrosophic Structures [based on the numerical components  $t =$  truth,  $i =$  indeterminacy,  $f =$  falsehood] are different from the *Neutrosophic Algebraic Structures* [based on neutrosophic numbers of the form  $a + bI$ ]. We may rename the last ones as *I-Neutrosophic Algebraic Structures* (meaning: algebraic structures based on literal indeterminacy "I" only). But we can combine both of them and obtain a  $(t, i, f)$ -I-Neutrosophic Algebraic Structures, i.e. algebraic structures based on neutrosophic numbers of the form  $a + bI$ , but this structure also having indeterminacy of the form  $(t, i, f) \neq (1, 0, 0)$  related to the structure space (elements which only partially belong to the space, or elements we know nothing if they belong to the space or not) or indeterminacy related to at least an axiom (or law) acting on the structure space. Even more, we can generalize them to *Refined (t, i, f)- Refined I-Neutrosophic Algebraic Structures*, or  $(t_j, i_k, f_l)$ -I-Neutrosophic Algebraic Structures.

### 6 Example of Refined I-Neutrosophic Algebraic Structure

Let the indeterminacy  $I$  be split into  $I_1 =$  contradiction (i.e. truth and falsehood simultaneously),  $I_2 =$  ignorance (i.e. truth or falsehood), and  $I_3 =$  vagueness, and the corresponding 3-refined neutrosophic numbers of the form  $a + b_1I_1 + b_2I_2 + b_3I_3$ .

Let  $(G, *)$  be a groupoid. Then the 3-refined I-neutrosophic groupoid is generated by  $I_1, I_2, I_3$  and  $G$  under  $*$  and it is denoted by  $N_3(G) = \{(G \cup I_1 \cup I_2 \cup I_3), *\} = \{a + b_1I_1 + b_2I_2 + b_3I_3 / a, b_1, b_2, b_3 \in G\}$ .

**7 Example of Refined (t, i, f)-Neutrosophic Structure**

Let (t, i, f) be split as (t<sub>1</sub>, t<sub>2</sub>; i<sub>1</sub>, i<sub>2</sub>; f<sub>1</sub>, f<sub>2</sub>, f<sub>3</sub>). Let H = ( {h<sub>1</sub>, h<sub>2</sub>, h<sub>3</sub>}, # ) be a groupoid, where h<sub>1</sub>, h<sub>2</sub>, and h<sub>3</sub> are real numbers. Since the elements h<sub>1</sub>, h<sub>2</sub>, h<sub>3</sub> only partially belong to H in a refined way, we define a refined (t, i, f)-neutrosophic groupoid { or refined (2; 2; 3)-neutrosophic groupoid, since t was split into 2 parts, I into 2 parts, and t into 3 parts } as H = {h<sub>1</sub>(0.1, 0.1; 0.3, 0.0; 0.2, 0.4, 0.1), h<sub>2</sub>(0.0, 0.1; 0.2, 0.1; 0.2, 0.0, 0.1), h<sub>3</sub>(0.1, 0.0; 0.3, 0.2; 0.1, 0.4, 0.0)}.

**8 Examples of (t, i, f)-I-Neutrosophic Algebraic Structures**

**8.1 Indeterminate Space (due to Unknown Element); with Neutrosophic Number included**

Let B = {2+5I, -I, -4, b(0, 0.9, 0)} a neutrosophic set, which contains two neutrosophic numbers, 2+5I and -I, and we know about the element b that its appurtenance to the neutrosophic set is 90% indeterminate.

**8.2 Indeterminate Space (due to Partially Known Element); with Neutrosophic Number included**

Let C = {-7, 0, 2+I(0.5, 0.4, 0.1), 1I(0.9, 0, 0)} , which contains a neutrosophic number 2+I, and this neutrosophic number is actually only partially in C; the element 1I is also partially in C.

**8.3 Indeterminacy Axiom (Law)**

Let D = [0+0I, 1+1I] = {c+dI, where c, d ∈ [0, 1]}. One defines the binary law # in the following way:

$$\#: D \times D \rightarrow D$$

$$x \# y = (x_1 + x_2I) \# (y_1 + y_2I) = [(x_1 + x_2)/y_1] + y_2I,$$

but this neutrosophic law is undefined (indeterminate) when y<sub>1</sub> = 0.

**8.4 Little Known or Completely Unknown Axiom (Law)**

Let us reconsider the same neutrosophic set D as above. But, about the binary neutrosophic law ⊕ that D is endowed with, we only know that it associates the neutrosophic numbers 1+I and 0.2+0.3I with the neutrosophic number 0.5+0.4I, i.e.

$$(1+I) \oplus (0.2+0.3I) = 0.5+0.4I.$$

There are many cases in our world when we barely know some axioms (laws).

**9 Examples of Refined (t, i, f)- Refined I-Neutrosophic Algebraic Structures**

We combine the ideas from Examples 5 and 6 and we construct the following example.

Let's consider, from Example 5, the groupoid (G, \*), where G is a subset of positive real numbers, and its extension to a 3-refined I-neutrosophic groupoid, which was generated by I<sub>1</sub>, I<sub>2</sub>, I<sub>3</sub> and G under the law \* that was denoted by N<sub>3</sub>(G) = { a+b<sub>1</sub>I<sub>1</sub>+b<sub>2</sub>I<sub>2</sub>+b<sub>3</sub>I<sub>3</sub> / a, b<sub>1</sub>, b<sub>2</sub>, b<sub>3</sub> ∈ G }.

We then endow each element from N<sub>3</sub>(G) with some (2; 2; 3)-refined degrees of membership/ indeterminacy/ nonmembership, as in Example 6, of the form (T<sub>1</sub>, T<sub>2</sub>; I<sub>1</sub>, I<sub>2</sub>; F<sub>1</sub>, F<sub>2</sub>, F<sub>3</sub>), and we obtain a N<sub>3</sub>(G)<sub>(2;2;3)</sub> = { a+b<sub>1</sub>I<sub>1</sub>+b<sub>2</sub>I<sub>2</sub>+b<sub>3</sub>I<sub>3</sub>(T<sub>1</sub>, T<sub>2</sub>; I<sub>1</sub>, I<sub>2</sub>; F<sub>1</sub>, F<sub>2</sub>, F<sub>3</sub>) / a, b<sub>1</sub>, b<sub>2</sub>, b<sub>3</sub> ∈ G }, where

$$T_1 = \frac{a}{a+b_1+b_2+b_3}, T_2 = \frac{0.5a}{a+b_1+b_2+b_3};$$

$$I_1 = \frac{b_1}{a+b_1+b_2+b_3}, I_2 = \frac{b_2}{a+b_1+b_2+b_3};$$

$$F_1 = \frac{0.1b_3}{a+b_1+b_2+b_3}, F_2 = \frac{0.2b_1}{a+b_1+b_2+b_3}, F_3 = \frac{b_2+b_3}{a+b_1+b_2+b_3}.$$

Therefore, N<sub>3</sub>(G)<sub>(2;2;3)</sub> is a refined (2; 2; 3)-neutrosophic groupoid and a 3-refined I-neutrosophic groupoid.

**10 Neutrosophic Geometric Examples**

**10.1 Indeterminate Space**

We might not know if a point P belongs or not to a space S [we write P(0, I, 0), meaning that P's indeterminacy is I, or completely unknown, with respect to S].

Or we might know that a point Q only partially belongs to the space S and partially does not belong to the space S [for example Q(0.3, 0.4, 0.5), which means that with respect to S, Q's membership is 0.3, Q's indeterminacy is 0.4, and Q's non-membership is 0.5].

Such situations occur when the space has vague or unknown frontiers, or the space contains ambiguous (not well defined) regions.

**10.2 Indeterminate Axiom**

Also, an axiom (α) might not be well defined on the space S, i.e. for some elements of the space the axiom (α) may be valid, for other elements of the space the axiom (α) may be indeterminate (meaning neither valid, nor invalid), while for the remaining elements the axiom (α) may be invalid.

As a concrete example, let's say that the neutrosophic values of the axiom (α) are (0.6, 0.1, 0.2) = (degree of validity, degree of indeterminacy, degree of invalidity).

**11 (t, i, f)-Neutrosophic Geometry as a Particular Case of (t, i, f)-Neutrosophic Structures**

As a particular case of (t, i, f)-neutrosophic structures in geometry, one considers a (t, i, f)-Neutrosophic Geometry as a geometry which is defined either on a space

with some indeterminacy (i.e. a portion of the space is not known, or is vague, confused, unclear, imprecise), or at least one of its axioms has some indeterminacy of the form  $(t, i, f) \neq (1, 0, 0)$  (i.e. one does not know if the axiom is verified or not in the given space, or for some elements the axiom is verified and for others it is not verified).

This is a generalization of the *Smarandache Geometry* (SG) [57-75], where an axiom is validated and invalidated in the same space, or only invalidated, but in multiple ways. Yet the SG has no degree of indeterminacy related to the space or related to the axiom.

A simple *Example of a SG* is the following – that unites Euclidean, Lobachevsky-Bolyai-Gauss, and Riemannian geometries altogether, in the same space, considering the Fifth Postulate of Euclid: in one region of the SG space the postulate is validated (only one parallel through a point to a given line), in a second region of SG the postulate is invalidated (no parallel through a point to a given line – elliptical geometry), and in a third region of SG the postulate is invalidated but in a different way (many parallels through a point to a given line – hyperbolic geometry). This simple example shows a hybrid geometry which is partially Euclidean, partially Non-Euclidean Elliptic, and partially Non-Euclidean Hyperbolic. Therefore, the fifth postulate (axiom) of Euclid is true for some regions, and false for others, but it is not indeterminate for any region (i.e. not knowing how many parallels can be drawn through a point to a given line).

We can extend this hybrid geometry adding a new space region where one does not know if there are or there are not parallels through some given points to the given lines (i.e. the Indeterminate component) and we form a more complex  $(t, i, f)$ -Neutrosophic Geometry.

## 12 Neutrosophic Algebraic Examples

### 12.1 Indeterminate Space (due to Unknown Element)

Let the set (space) be  $NH = \{4, 6, 7, 9, a\}$ , where the set  $NH$  has an unknown element "a", therefore the whole space has some degree of indeterminacy. Neutrosophically, we write  $a(0, 1, 0)$ , which means the element  $a$  is 100% unknown.

### 12.2 Indeterminate Space (due to Partially Known Element)

Given the set  $M = \{3, 4, 9(0.7, 0.1, 0.3)\}$ , we have two elements 3 and 4 which surely belong to  $M$ , and one writes them neutrosophically as  $3(1, 0, 0)$  and  $4(1, 0, 0)$ , while the third element 9 belongs only partially (70%) to  $M$ , its appurtenance to  $M$  is indeterminate (10%), and does not belong to  $M$  (in a percentage of 30%).

Suppose the above neutrosophic set  $M$  is endowed with a neutrosophic law  $*$  defined in the following way:

$$x_1(t_1, i_1, f_1) * x_2(t_2, i_2, f_2) = \max\{x_1, x_2\}(\min\{t_1, t_2\}, \max\{i_1, i_2\}, \max\{f_1, f_2\}),$$

which is a neutrosophic commutative semigroup with unit element  $3(1, 0, 0)$ .

Clearly, if  $x, y \in M$ , then  $x*y \in M$ . Hence the neutrosophic law  $*$  is well defined.

Since  $\max$  and  $\min$  operators are commutative and associative, then  $*$  is also commutative and associative.

If  $x \in M$ , then  $x*x = x$ .

Below, examples of applying this neutrosophic law  $*$ :

$$3*9(0.7, 0.1, 0.3) = 3(1, 0, 0)*9(0.7, 0.1, 0.3) = \max\{3, 9\}(\min\{1, 0.7\}, \max\{0, 0.1\}, \max\{0, 0.3\}) = 9(0.7, 0.1, 0.3).$$

$$3*4 = 3(1, 0, 0)*4(1, 0, 0) = \max\{3, 4\}(\min\{1, 1\}, \max\{0, 0\}, \max\{0, 0\}) = 4(1, 0, 0).$$

### 12.3 Indeterminate Law (Operation)

For example, let the set (space) be  $NG = (\{0, 1, 2\}, /)$ , where "/" means division.

$NG$  is a  $(t, i, f)$ -neutrosophic groupoid, because the operation "/" (division) is partially defined, partially indeterminate (undefined), and partially not defined. Undefined is different from not defined. Let's see:

$2/1 = 1$ , which belongs to  $NG$ ; {defined}.

$1/0 = \text{undefined}$ ; {indeterminate}.

$1/2 = 0.5$ , which does not belong to  $NG$ ; {not defined}.

So the law defined on the set  $NG$  has the properties that:

- applying this law to some elements, the results are in  $NG$  [well defined law];
- applying this law to other elements, the results are not in  $NG$  [not well defined law];
- applying this law to again other elements, the results are undefined [indeterminate law].

We can construct many such algebraic structures where at least one axiom has such behavior (such indeterminacy in principal).

### Websites at UNM for Neutrosophic Algebraic Structures and respectively Neutrosophic Geometries

<http://fs.gallup.unm.edu/neutrosophy.htm>, and <http://fs.gallup.unm.edu/geometries.htm> respectively.

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