

# Neutrosophic Rayleigh Model with Some Basic Characteristics and Engineering Applications

Zahid Khan<sup>1</sup>, Muhammad Gulistan<sup>1</sup>, Nasreen Kausar<sup>2</sup>, Choonkil Park<sup>3</sup>

<sup>1</sup>Department of Mathematics and Statistics, Hazara University Mansehra, Pakistan

<sup>2</sup>Department of Mathematics, University of Agriculture Faisalabad, Pakistan

<sup>3</sup>Department of Mathematics, Research Institute for Natural Sciences, Hanyang University, Seoul 04763, Korea

Corresponding authors: C. Park (e-mail: baak@hanyang.ac.kr) and Z. Khan (e-mail: zahidkhan@hu.edu.pk).

**ABSTRACT** The fundamentals of neutrosophic statistics provide a new basis for working with indeterminate data problems. In this study, the notion of the neutrosophic Rayleigh distribution ( $RD_N$ ) has been introduced. The neutrosophic extension of the classical Rayleigh model with several application areas is highlighted. The major characteristics of the proposed distribution are described in a way that suggested model can be utilized in different situations involving undetermined, vague and fuzzy data. The usage of proposed distribution notably in the domain of statistical process control (SPC) is considered. The classical structure of  $V_{SQR}$ -chart is not capable of capturing uncertainty on studied variables. The mathematical structure of the  $V_{NR}$ -chart based on the proposed neutrosophic distribution has been developed. The neutrosophic parameters of the proposed  $V_{NR}$ -chart with other related performance metrics such as neutrosophy run length ( $ARL_N$ ) and neutrosophy power curve ( $PC_N$ ) are established. The proposed chart's performance in a neutrosophic environment is also evaluated to the existing model. Results from this comparative analysis reveal that the suggested  $V_{NR}$ -chart outperforms its current equivalent in terms of neutrosophic statistical power. Finally, a charting structure of proposed design for service life of ball bearings data is considered with a view to support implementation procedure of the proposed neutrosophic design in real-world scenarios.

**INDEX TERMS** Neutrosophic logic, Rayleigh model, control chart, neutrosophic parameters

## I. INTRODUCTION

Variability is an inevitable phenomenon of the production industry. It is often due to normal causes and specific causes of variation. Quality management utilizes different management and engineering methods to manufacture quality goods by eliminating abnormal rooted variations [1]. The process operating only under irregular variations is considered out-of-control (OC) and the process working underlying normal causes of variation is called in-control (IC) in statistical terms. The SPC is a common technique that involves statistical tools to precisely measure variations in the parameters of the production or manufacturing process [2]. A statistical quality control chart, an effective technique in the SPC, is commonly practiced in service and manufacturing industries to analyze the behavior of processes in addition to enhancing their productivity [3]. The primary aim of the control chart is to identify irregularity in manufactured items as soon as possible, so that the process could be terminated on time before the manufacturing of faulty products [4]. The Shewhart chart, originally introduced by Walter A. Shewhart, is a very trendy process predictive method that can be implemented and interpreted easily. Due

to its easy implementation and broad usage, the Shewhart chart is not frequently used in service industries and modern processes where minor process changes can impose severe financial losses [5]. It is therefore vital to use memory-type charts that are more responsive to moderate-to-small changes in the target parameters [6]. On the contrary, SPC problems may involve uncertainty, as are most of the true world systems. When there is uncertainty in the system and even if the quality characteristics are portrayed by human perception, the process cannot be precisely described by control charts mentioned above [7]. In order to explain and model such problems, fuzzy set theory is therefore used [8]. A brief application of fuzzy charts can be originated in studies [9]–[11]. The fuzzification based control charts are more sensitive in general than standard control charts [8]. The idea of Neutrosophic Set (NS) is a broader platform that expands the notions of the fuzzy and classical sets [12].

The occurrence of truth, false and indeterminate situations are considered in the philosophy of the NS. The notion of the NS is now extended to various fields of study [13]. There are several real-world circumstances where the collected data might be indeterminate. For applications containing imprecise data are handled by different researchers using the neutrosophic statistics (NST) [14]–[16]. The classical approach of the conventional statistical techniques has been generalized in the area of NST with the purpose to deal with vagueness in processing data. It is not possible to use a traditional control chart approach when underlying data consists of Incomplete, vague, or uncertain data on quality characteristics. Statistical methods integrated with the neutrosophic logic have been recently developed in the literature of SPC by numerous researchers such as Aslam proposed the neutrosophic version of the acceptance sampling plan in the domain of SPC [17]. Aslam and Raza suggested a sampling plan for several production lines employing the NST [18]. Whereas the more facts on the usage of NST in structuring the Shewhart charts can be found in [18]–[22]. When normality presumption is severely violated, the application of widely used control charts is drastically less prudent. The  $V_{SQR}$  is one of such designs to accommodate this non-normality situation for quality data that best described by the classical Rayleigh model [23]. Rayleigh distribution (RD) is one of the statistical distributions that attracted various researchers due to its applications in vast engineering related problems [24], [25].

In this work, we are intended to describe some characteristics of the  $RD_N$  and the neutrosophic extension of the  $V_{SQR}$ -chart that can deal the indeterminate observations in Rayleigh distributed quality characteristics. The proposed  $V_{NR}$  design

is rooted on the  $RD_N$  and represents the generalization of the conventional  $V_{SQR}$ -chart.

The remainder of the study is arranged as follows: Section 2 provides the introduction of the  $RD_N$ . The suggested control chart based on the  $RD_N$  is given in Section 3. The performance measure of the proposed neutrosophic design is described in Section 4. A comparison study of the  $V_{NR}$  design is given in Section 5. A real example of the functional implementation of the proposed  $V_{NR}$ -chart has been explained in Section 6. The main results of the research are outlined and concluded in Section 7.

## II. Neutrosophic Rayleigh Model

Definition: The Neutrosophic model of the Rayleigh distribution with imprecision in the scale parameter  $\theta_N$  has the following characteristics:

$$f(z, \theta_N) = \frac{z}{\theta_N^2} e^{-\frac{1}{2}\left(\frac{z}{\theta_N}\right)^2}, \quad \theta_N > 0, Z > 0. \quad (1)$$

$$F(z, \theta_N) = 1 - e^{-\frac{1}{2}\left(\frac{z}{\theta_N}\right)^2}, \quad \theta_N > 0, Z > 0. \quad (2)$$

where  $\theta_N \in [\theta_l, \theta_u]$ ,  $f(z, \theta_N)$  and  $F(z, \theta_N)$  denote the neutrosophic density function ( $PDF_N$ ) and characteristic function ( $CDF_N$ ) respectively of the  $RD_N$ . Based on the neutrosophic version of the Rayleigh model primary characteristics of the neutrosophic random  $Z$  are given by:

$$\mu_N = \theta_N \sqrt{\frac{\pi}{2}}, \quad \sigma_N^2 = \theta_N^2 (2 - \pi/2)^2 \quad (3)$$

where  $\mu_N$  and  $\sigma_N^2$  are mean and variance respectively of the  $RD_N$ .

The graphical expressions of the  $f(z, \theta_N)$  and  $F(z, \theta_N)$  for the neutrosophic Rayleigh variable  $Z$  with imprecise parameter  $\theta_N = [0.5, 0.75]$  is shown in the Figure 1.

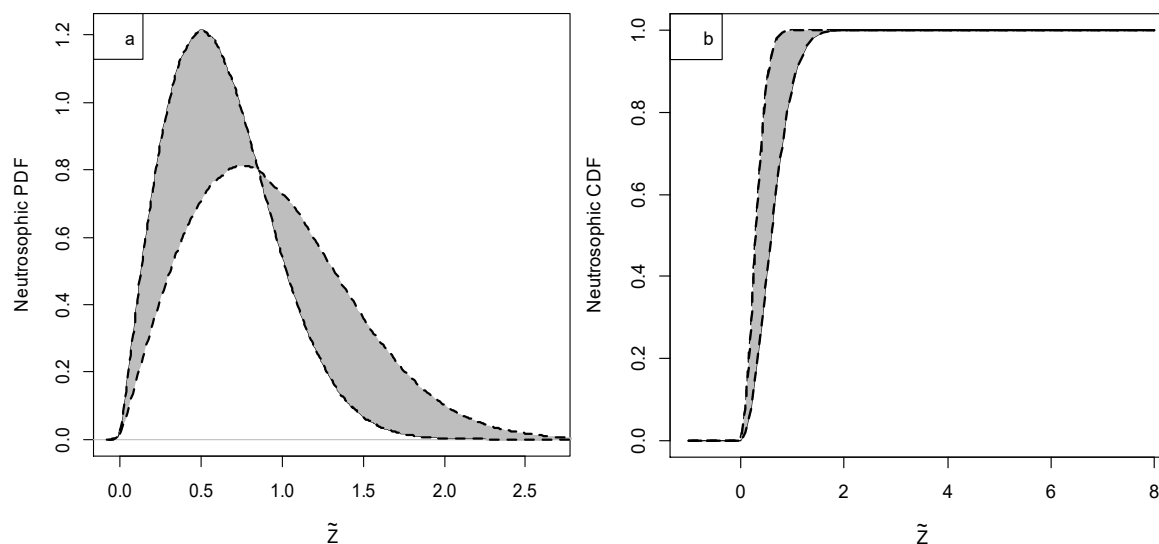


FIGURE 1.  $PDF_N$  and  $CDF_N$  of the neutrosophic Rayleigh random variable

From the plot in Figure 1(a) the neutrosophic region can be seen with shaded region between the dotted lines and curve is asymmetric curve for the indeterminate value [0.5, 0.75] of the scale parameter  $\theta_N$ . An infinite number of structures is possible for the  $PDF_N$ , since the neutrosophic scale parameter affects the form of the curve. However the large value of  $\theta_N$  may result in the symmetric behavior of the  $PDF_N$ . Figure 1 (b) denotes the typical non-decreasing behavior of the underlying  $CDF_N$  curve for the same selected values of the  $\theta_N$  which is one of the most general descriptions of a distribution function.

Rayleigh distribution is widely employed to describe the wind speed data, signals data in communications, lifetimes of different objects in reliability studies, modeling the noise factor in magnetic imaging and in SPC for designing the control chart structure that may employ for monitoring the stability of the distribution parameter. Here are a few examples of neutrosophic version of the Rayleigh distribution for the purpose to underline its significant in a variety of fields.

**Example 1:** Let the neutrosophic Rayleigh distribution as defined in (1) is used to describe the repair time in hours of a manufacturing machine with mean time [30, 45] hours. Determine the probability that repair time does not exceed 35 hours.

**Solution:** Given that  $\mu_N = [30, 45]$  so by using relation given in (3) we can get neutrosophic scale parameter  $\theta_N \cong [24, 36]$ .

Now using (2), we have found the desired probability as:

$$\begin{aligned} P(Z \leq 35) &= 1 - e^{-\frac{1}{2}\left(\frac{z}{\theta_N}\right)^2} \\ &= 1 - e^{-\frac{1}{2}\left(\frac{35}{\frac{36}{24}}\right)^2} \\ &= 1 - e^{-[0.472, 1.063]} \end{aligned}$$

**Example 2:** Let the daily electricity consumption in different estates of KPK province in Pakistan is a neutrosophic random variable Z which is best described by  $PDF_n$  as given in (1) with neutrosophic scale parameter  $\theta_N = [1000, 1500]$ .

The power plants of this province have a capacity of 2762 Megawatt (MW). On any given day, what is the probability that power supply would be inadequate?

**Solution:** Power supply will be inadequate if demand of power is more than installed capacity

It follows:

$$\begin{aligned} P(Z > 2762) &= 1 - P(Z \leq 2762) \\ &= 1 - e^{-\frac{1}{2}\left(\frac{2762}{\frac{1500}{1000}}\right)^2} \\ &= [0.816, 0.978] \end{aligned}$$

Hence the approximate probability of insufficient supply will be within 0.82 to 0.98.

### III. PROPOSED CONTROL CHART

In this section proposed chart based on the  $RD_N$  has been proposed. The value of the characterized neutrosophic scale parameter  $\theta_N$  is typically not determined in real-life

scenarios. Several estimation techniques may be used to find the unknown quantity  $\sigma$  [26]. Based on the maximum likelihood (ML) strategy, an estimate of  $\theta_N$  is provided by [23]:

$$\hat{\theta}_N = \sqrt{\frac{\sum_{i=1}^{\tilde{m}} X_{iN}^2}{2\tilde{m}}} \quad (4)$$

where  $\tilde{m} = [m_L, m_U]$  is the neutrosophic sample size which turn to classical sample size when  $m_L = m_U = m$ .

We need to identify the distribution of the neutrosophic  $\hat{\theta}_N$ -statistic for structuring the parameters of the proposed  $V_N$ -chart. The statistic  $\hat{\theta}$  is connected with the chi ( $\chi$ ) random variable  $V$  as follows []:

$$\hat{\theta}_N = \frac{\sigma}{\sqrt{2m}} V \quad (5)$$

where  $V$  follows  $\chi$ -distribution with  $2m$  degree of freedom ( $df$ ). Now it has been assumed that imprecise values of  $\sigma$  and  $m$  are given rather than crisp values.

Equation (5) can be rewritten under the neutrosophic condition as:

$$\hat{\theta}_N = \frac{\sigma_N}{\sqrt{2\tilde{m}}} \tilde{V} \quad (6)$$

where random variable  $\tilde{V}$  follows the neutrosophic  $\chi$ -distribution ( $\chi_N$ ) with  $2\tilde{m}$   $df$ .

Utilizing (6) the neutrosophic characteristics of the estimator  $\hat{\theta}_N$  can be found as:

$$\left. \begin{aligned} E(\hat{\theta}_N) &= \sigma_N A(\tilde{m}) \\ V(\hat{\theta}_N) &= \sigma_N^2 [1 - A(\tilde{m})^2] \end{aligned} \right\} \quad (7)$$

where  $A(\tilde{m}) = \frac{1}{\sqrt{(\tilde{m})}} \frac{\Gamma(\frac{(\tilde{m})+1}{2})}{\Gamma(\tilde{m})}$  is constant and based on the neutrosophic sample size  $\tilde{m}$ .

Equation (7) indicates that statistic  $\hat{\theta}_N$  is biased estimator of  $\sigma_N$ . Suppose that  $k$  sample batches with imprecise values are provided for analysis and  $\hat{\theta}_{Ni}$  be the ML statistic of the  $i$ th sample batch then average defined on all  $k$  sample batches would be:

$$\bar{\theta}_N = \frac{\sum_{i=1}^k \hat{\theta}_{Ni}}{k} \quad (8)$$

Following (7) and (8) the  $\sigma_N$  can be estimated by an unbiased estimator as:

$$\hat{\sigma}_N = \frac{\bar{\theta}_N}{A(\tilde{m})} \quad (9)$$

The distribution of  $\hat{\theta}_N$  is asymmetric specifically for smaller values of  $\tilde{m}$ , so 3-sigma limits are not generally applicable due to unequal tail areas [27]. Probability limits (PL) are readily used to deal with this issue as a standard practice in SPC.

As  $\tilde{V}$  follows the neutrosophic chi distribution with  $2\tilde{m}$   $df$ ,  $\alpha$ th percentage point of the distribution is defined as:

$$F_{\chi}(\tilde{v}) = \alpha \quad (10)$$

Consequently simplification of (10) and (5) follows

$$\hat{\theta}_N = \frac{\sigma_N}{\sqrt{2\tilde{m}}} F^{-1}_{\chi}(\alpha) \quad (11)$$

Thus the PL of the proposed  $V_N$ -chart are then obtained by:

$$\left. \begin{aligned} \overline{UPL} &= \frac{\sigma_N}{\sqrt{2\tilde{m}}} F^{-1}_{\chi} \left(1 - \frac{\alpha}{2}\right) = \sigma_N \tilde{Q}_1 \\ \overline{LPL} &= \frac{\sigma_N}{\sqrt{2\tilde{m}}} F^{-1}_{\chi} \left(\frac{\alpha}{2}\right) = \sigma_N \tilde{Q}_2 \end{aligned} \right\} \quad (12)$$

where  $\tilde{Q}_1 = \frac{F^{-1}\chi(1-\frac{\alpha}{2})}{\sqrt{2\tilde{m}}} = [Q_{1L}, Q_{1U}]$  and  $\tilde{Q}_2 = \frac{F^{-1}\chi(\frac{\alpha}{2})}{\sqrt{2\tilde{m}}} = [Q_{2L}, Q_{2U}]$ .

When the parameter of the distributed quality characteristic of the  $RD_N$  is not specified, it would be calculated using an estimator given in (9). Thus  $PL$  based on the estimated parameters can be modified as:

$$\left. \begin{aligned} \widetilde{UPL} &= \frac{\hat{\sigma}_N}{\sqrt{2\tilde{m}}} F^{-1}\chi\left(1 - \frac{\alpha}{2}\right) = \bar{\theta}_N \tilde{Q}_3 \\ \widetilde{LPL} &= \frac{\hat{\sigma}_N}{\sqrt{2\tilde{m}}} F^{-1}\chi\left(\frac{\alpha}{2}\right) = \bar{\theta}_N \tilde{Q}_4 \end{aligned} \right\} \quad (13)$$

where  $\tilde{Q}_3 = \frac{F^{-1}\chi(1-\frac{\alpha}{2})}{A(\tilde{m})\sqrt{2\tilde{m}}} = [Q_{3L}, Q_{3U}]$  and  $\tilde{Q}_4 = \frac{F^{-1}\chi(\frac{\alpha}{2})}{A(\tilde{m})\sqrt{2\tilde{m}}} = [Q_{4L}, Q_{4U}]$

The classical pair of crisp values  $(Q_1, Q_2)$  and  $(Q_3, Q_4)$  for fixed risk factor  $\alpha$  and at various values of  $\tilde{m}$  are easily calculated and available in [23]. The 3-sigma limits can be developed in a similar fashion, however are not focused here because of asymmetric behavior of the underlying statistic  $\hat{\theta}_N$  particular for a smaller indeterminate values of  $\tilde{m}$ .

#### IV. Performance Analysis

In this section, the performance metrics used in this study have been described, followed by a comparative analysis, and outlined their computational algorithm. To evaluate the sensitivity of the proposed  $V_{NR}$ -chart the notions of the neutrosophic operating characteristic curve ( $OC_N$ ),  $ARL_N$  and  $PC_N$  are described. There are widely used metrics to assess the efficiency of proposed design in classical control charts theory [28]. The  $OC_N$  and  $PC_N$  functions are customary employed to characterize the control chart's ability to detect a difference in the observed quality phase. The  $ARL_N$  statistic, on the other hand, describes the average samples taken prior to the identification of abrupt change in the target parameter for a system operating under any special cause. The control chart method is similar to the hypothesis evaluation strategy, so, the  $V_{NR}$ -chart's ability to not detect change in target parameter would be defined in accordance with neutrosophic type II error as follows:

$$\beta_N = P[\widetilde{LCL} \leq \hat{\theta}_N \leq \widetilde{UCL} | H_1] \quad (14)$$

Here  $H_1: \sigma_N = \sigma_{N1}$  stands for alternative hypothesis with  $\sigma_{N1} = \delta\sigma_{N0}$ ,  $\delta$  is shift constant and  $\sigma_{N0} = [\sigma_{L0}, \sigma_{U0}]$  is neutrosophic IC target parameter of the  $RD_N$ .

Equation (14) further can be written as:

$$\beta = F_\chi(\delta\tilde{Q}_1\sqrt{2\tilde{m}}) - F_\chi(\delta\tilde{Q}_2\sqrt{2\tilde{m}}) \quad (15)$$

where  $F_\chi$  is distribution function of the  $\chi_N$  with  $2\tilde{m}$  df.

Using (15)  $ARL_{N1}$  for OC process can be expressed as:

$$ARL_{N1} = \frac{1}{1 - F_\chi(\delta\tilde{Q}_1\sqrt{2\tilde{m}}) + F_\chi(\delta\tilde{Q}_2\sqrt{2\tilde{m}})} \quad (16)$$

where  $1 - F_\chi(\delta\tilde{Q}_1\sqrt{2\tilde{m}}) + F_\chi(\delta\tilde{Q}_2\sqrt{2\tilde{m}}) = 1 - \beta$  constitutes the power of the proposed  $V_{NR}$ -chart.

Note that the shift constant values  $\delta > 1$  and  $\delta < 1$  in (16) determine the downward and upward shifts respectively in the monitoring parameter whereas the value  $\delta = 1$  stands for a process working at the target value  $\sigma_{N0}$ . In order to determine the use of (16), let's assume  $\delta > 1$  and we are

trying to work out how many samples are expected on average to identify a specific shift.

The  $ARL_N$  curve is provided in Figure 2 for the proposed chart for a neutrosophic sample size  $\tilde{m} = [2, 3]$  at  $\alpha = 0.025$ .

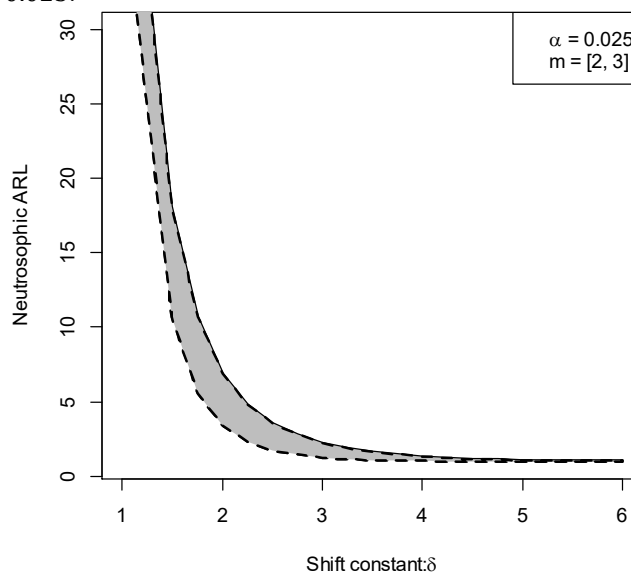


FIGURE 2 Construction of the  $ARL_{N1}$  for  $V_{NR}$ -chart

Figure 2 represents the geometric shape of the run length distribution for a particular neutrosophic sample size  $\tilde{m}$  and variety of curves can be constructed in similar way for other values of  $\tilde{m}$ . The curve in Figure 2 would be helpful to determine the average number samples needed for a particular shift in the target parameter. As an example, consider a shift of quantity  $2\sigma_{N0}$  in the target parameter, on average [4, 6] samples would be required to initiate this particular shift. Besides that, if we increase the shift size, this  $ARL_{N1}$  tends to constant value 1. For a better clarity, the proposed design's run length characteristic is also evaluated at different sample sizes in Table 1 with fixed false alarm rate  $\alpha = 0.025$ .

TABLE 1 THE  $ARL_N$  PROFILE OF THE PROPOSED CHART

Shift constant ( $\delta$ )	Neutrosophic Sample Size ( $\tilde{m}$ )		
	[2, 3]	[4, 6]	[7, 9]
	$ARL_N$		
1.00	[39.81, 39.99]	[39.95, 40.15]	[40.04, 40.08]
1.50	[10.69, 18.11]	[4.00, 7.18]	[2.30, 3.21]
2.00	[3.37, 6.90]	[1.32, 2.13]	[1.05, 1.17]
2.50	[1.75, 3.56]	[1.02, 1.25]	[1.00, 1.00]
3.00	[1.25, 2.25]	[1.00, 1.05]	[1.00, 1.00]
3.50	[1.08, 1.65]	[1.00, 1.00]	[1.00, 1.00]
4.00	[1.02, 1.33]	[1.00, 1.00]	[1.00, 1.00]
4.50	[1.00, 1.17]	[1.00, 1.00]	[1.00, 1.00]
5.00	[1.00, 1.09]	[1.00, 1.00]	[1.00, 1.00]

Results in Table 1 indicate that the measured  $ARL_{N1}$  value is closer to the expected value of 40, particularly when the sample size is greater and the process is IC i.e.,  $\delta = 1$ . The  $V_{NR}$ -chart is extremely effective for determining moderate to large changes in the target parameter, as observed by these  $ARL_{N1}$  values. Additionally, by changing the neutrosophic target parameter to  $\sigma_{N1}$ , the performance of the  $V_{NR}$ -chart in terms of  $PC_N$  function can be evaluated for different values of  $\tilde{m}$  and  $\alpha$ . For example, the  $PC_N$  computed for  $\tilde{m} = [3, 5]$  with false rate  $\alpha = 0.025$  is shown in Figure 3.

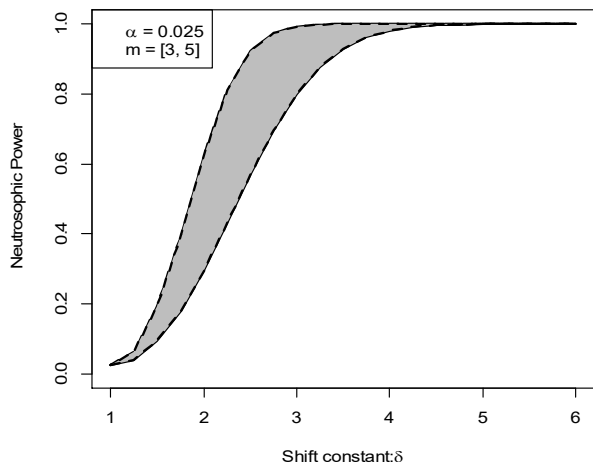


FIGURE 3. The neutrosophic power curve

The neutrosophic power plot in Figure 3 also reveals that the proposed  $V_{NR}$  control chart essentially detects various amounts of changes in the monitoring parameter. This curve, provides the power platform of the proposed chart for detecting a certain amount of shift in the monitoring parameter. For instance, the  $V_{NR}$ -chart provides neutrosophic power in range of  $[0.799, 0.993]$ , for detecting a shift of  $3\sigma_{N0}$  in scale parameter of the  $RD_N$ .

### V. Comparison Analysis

In this part, the proposed chart's performance is compared to other existing design used for monitoring the neutrosophic parameter of the  $RD_N$ . The performance of  $V_{NR}$ -chart has been compared with existing model of the  $V_{SQR}$ -chart under the indeterminate environment.

For this comparison, a number of available metrics can be used; however, power curves are commonly used in several studies [29], [30]. The proposed chart power in (16) is the probability of accurately rejecting  $H_0$ . In our case, the power of the  $V_{NR}$ -chart is characterized if the calculated statistics ( $\hat{\theta}_{Ni}$ ) exceed the lower and upper calculated limits for a given value of false alarm probability  $\alpha$  and neutrosophic sample size  $\tilde{m}$ . Any control chart that has a higher probability of appropriately rejecting  $H_0$  is deemed efficient. The power of the suggested chart and its equivalent  $V_{SQR}$  has been estimated using this method for fixed values of  $\alpha$  and  $\tilde{m}$  in Figure 4.

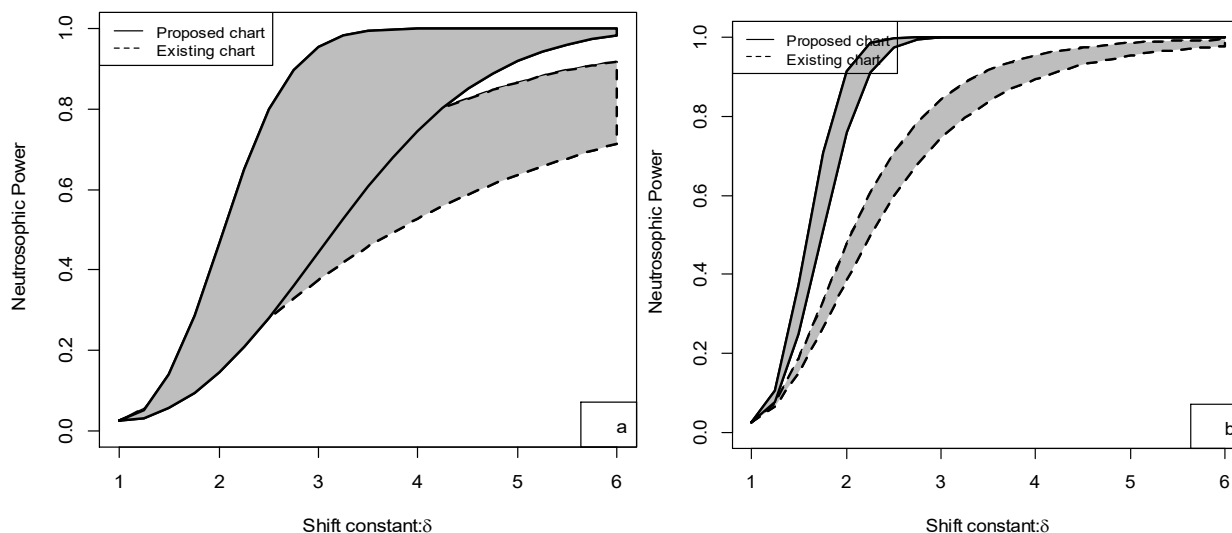


FIGURE 4 Power comparisons at  $\alpha = 0.025$  and (a) neutrosophic sample size  $\tilde{m} = [2, 4]$  and (b) neutrosophic sample size  $\tilde{m} = [6, 8]$



Neutrosophic power curves in Figure 4 show that power of both charts increase with increased in shift constant i.e.,  $\delta > 1$ . When the process is under control with a shift constant  $\delta = 1$ , the power is even similar to the theoretical false rate probability  $\alpha = 0.025$ . For each shift in scale parameter power is given in an imprecise range and represented by the shaded region. For instance, power of the  $V_{NR}$  control is about [0.4, 0.85] for detecting a shift of amount 3 at  $\tilde{m} = [2, 4]$  whereas existing design has approximately neutrosophic power in range [0.30, 0.65] for the same shift in the target parameter. If the sample size becomes larger, the disparity becomes larger. Thus, it is obvious from Figure 4 that the proposed  $V_{NR}$ -chart is more capable than the neutrosophic  $V$ -chart for detecting shifts in the parameter  $\sigma_{N0}$  for a given value of  $\tilde{m}$ .

### VI. REAL APPLICATION

In this part, a real data set has been utilized to demonstrate the computational procedure of the suggested chart illustrated in Section 3. Data used in analysis is originally analyzed by Lieblein and Zelen [31] with a view to model the service life of ball bearing data. Data is further analysis by many other others in their respective studies [32], [33]. The observations in this dataset represent the revolution (in million) of 23 ball bearing balls before failure occurred. The ball bearing data fits well with the Rayleigh distribution as discussed in [34]. Here this dataset collection is examined from the viewpoint of a neutrosophic environment. The data from the original source are exact numerical values, but neutrosophic data are produced according to the method reported in [20] to aid in understanding the preceding concept of the  $V_N$ -chart. The data produced in this way is now available in ranges rather than crisp values. The indeterminate data in ranges on ball bearing failure times are divided into seven subgroups, each with three observations listed in Table 2. The neutrosophic statistic  $\hat{\theta}_N$  is used in the proposed control chart to monitor the target parameter of the  $RD_N$ . As a result, the statistic  $\hat{\theta}_N$  for each subgroup is calculated and recorded in the fourth column of Table 2.

TABLE 2 NEUTROSOPHIC BALL BEARINGS FAILURE LIFE DATA

S. No	$x_{N1}$	$x_{N2}$	$x_{N3}$	$\hat{\theta}_N$
1	[0.70, 0.81]	[0.67, 0.73]	[0.80, 0.86]	[0.51, 0.57]
2	[0.63, 0.81]	[0.96, 1.04]	[1.06, 1.21]	[0.63, 0.73]
3	[0.35, 0.41]	[1.07, 1.26]	[0.60, 0.70]	[0.52, 0.61]
4	[0.70, 0.72]	[0.95, 1.35]	[0.85, 1.01]	[0.59, 0.75]
5	[1.12, 1.43]	[0.82, 1.02]	[0.34, 1.11]	[0.58, 0.85]
6	[0.47, 1.39]	[0.23, 0.74]	[0.07, 1.17]	[0.52, 0.80]
7	[0.85, 1.03]	[0.76, 0.95]	[0.41, 0.44]	[0.49, 0.60]

For the details in Table 3, the parameters of the  $V_{NR}$  control chart utilizing (13) are obtained as follows:  
 $\overline{UPL} = [0.95, 1.02]$ ,  $CL = [0.55, 0.70]$  and  $\overline{LPL} = [0.23, 0.29]$ .

Figure 5 shows a schematic representation of the proposed  $V_N$  control for the observed quality characteristic.

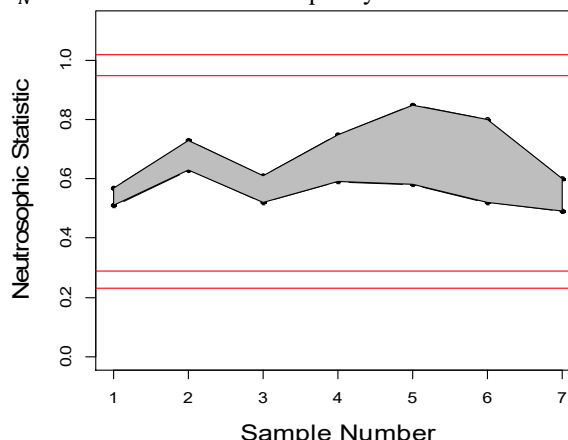


FIGURE 5 The construction of  $V_{NR}$  control chart for ball bearings life times data

The plotted neutrosophic statistics in Figure 5 have a random behavior and are within the control limits. Consequently, observed process may be inferred as in a state of statistical control.

### VII. CONCLUSION

In this work, the classical Rayleigh model has been extended in accordance with neutrosophic logic. Mathematical characteristics of the proposed distribution under an indeterminacy environment are described. Application areas of the  $RD_N$  have been provided for working data that contain vague, indeterminate and imprecise observations on studied variables. A new control chart based on the proposed  $RD_N$  is developed due to its adequacy of dealing vague data in the applications of SPC. The neutrosophic parameters,  $ARL_N$ ,  $PC_N$  and  $OC_N$  of the suggested chart have been derived. To illustrate the theoretical results, a simulation study is carried out and performance of the  $V_N$ -chart is compared with existing counterpart. Numerical results illustrate that proposed design is more effective in terms of identifying changes in the monitoring parameter of the  $RD_N$ .

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