

## Neutrosophic $e$ -Continuous Maps and Neutrosophic $e$ -Irresolute Maps

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**Abstract:** Aim of this present paper is to introduce and investigate new kind of neutrosophic continuous function called neutrosophic  $e$ -continuous maps in neutrosophic topological spaces and also relate with their near continuous maps. Also, a new irresolute map called neutrosophic  $e$ -irresolute maps in neutrosophic topological spaces is introduced. Further, discussed about some properties and characterization of neutrosophic  $e$ -irresolute maps in neutrosophic topological spaces.

**Keywords and phrases:** Neutrosophic  $e$ -open sets, neutrosophic  $e$ -continuous maps, neutrosophic  $eU_{\frac{1}{2}}$ -space and neutrosophic  $e$ -irresolute maps.

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### 1 Introduction

The concept of fuzzy set (briefly,  $fs$ ) was introduced by Lotfi Zadeh in 1965 [17], then Chang depended the fuzzy set to introduce the concept of fuzzy topological space (briefly,  $fts$ ) in 1968 [5]. After that the concept of fuzzy set was developed into the concept of intuitionistic fuzzy set (briefly,  $ifs$ ) by Atanassov in 1983 [2, 3, 4], the intuitionistic fuzzy set gives a degree of membership and a degree of non-membership functions. Coker in 1997 [5] relied on intuitionistic fuzzy set to introduced the concept of intuitionistic fuzzy topological space (briefly,  $ifts$ ). In 2005 Smaradache [13] study the concept of neutrosophic set (briefly,  $Ns$ ). After that and as developed the term of neutrosophic set, Salama has studied neutrosophic topological space (briefly,  $Nts$ ) and many of its applications [8, 9, 10, 11]. In 2012 Salama and Alblawi defined neutrosophic topological space [8]. Saha [7] defined  $\delta$ -open sets in topological spaces. Vadivel et al. [15] introduced  $\delta$ -open sets in a neutrosophic topological space. In 2008, Ekici [6] introduced the notion of  $e$ -open sets in a general topology. In 2014, Seenivasan et al. [12] introduced  $e$ -open sets in a topological space along with  $e$ -continuity. Vadivel et al. [16] studied fuzzy  $e$ -open sets in intuitionistic fuzzy topological space. In this paper, we develop the concept of neutrosophic  $e$  continuity in a topological spaces and also specialized some of their basic properties with examples. Also, we discuss about properties and characterization of neutrosophic  $e$ -irresolute maps.

### 2 Preliminaries

The needful basic definitions & properties of neutrosophic topological spaces are discussed in this section.

**Definition 2.1** [8] Let  $Y$  be a non-empty set. A neutrosophic set (briefly,  $N_s s$ )  $L$  is an object having the form  $L = \{hy, \mu_L(y), \sigma_L(y), \nu_L(y) : y \in Y\}$  where  $\mu_L \rightarrow [0, 1]$  denote the degree of membership function,  $\sigma_L \rightarrow [0, 1]$  denote the degree of indeterminacy function and  $\nu_L \rightarrow [0, 1]$  denote the degree of non-membership function respectively of each element  $y \in Y$  to the set  $L$  and  $0 \leq \mu_L(y) + \sigma_L(y) + \nu_L(y) \leq 3$  for each  $y \in Y$ .

**Remark 2.1** [8] A  $N_s s$   $L = \{hy, \mu_L(y), \sigma_L(y), \nu_L(y) : y \in Y\}$  can be identified to an ordered triple  $hy, \mu_L(y), \sigma_L(y), \nu_L(y) : y \in Y$  on  $Y$ .

**Definition 2.2** [8] Let  $Y$  be a non-empty set & the  $N_s s$ 's  $L$  &  $M$  in the form  $L = \{hy, \mu_L(y), \sigma_L(y), \nu_L(y) : y \in Y\}$ ,  $M = \{hy, \mu_M(y), \sigma_M(y), \nu_M(y) : y \in Y\}$ , then

- (i)  $0_N = hy, 0, 0, 1i$  and  $1_N = hy, 1, 1, 0i$ ,
- (ii)  $L \subseteq M$  iff  $\mu_L(y) \leq \mu_M(y)$ ,  $\sigma_L(y) \leq \sigma_M(y)$  &  $\nu_L(y) \geq \nu_M(y) : y \in Y$ ,
- (iii)  $L = M$  iff  $L \subseteq M$  and  $M \subseteq L$ ,
- (iv)  $1_N - L = \{hy, \nu_L(y), 1 - \sigma_L(y), \mu_L(y) : y \in Y\} = L^c$ ,
- (v)  $L \cup M = \{hy, \max(\mu_L(y), \mu_M(y)), \max(\sigma_L(y), \sigma_M(y)), \min(\nu_L(y), \nu_M(y)) : y \in Y\}$ ,
- (vi)  $L \cap M = \{hy, \min(\mu_L(y), \mu_M(y)), \min(\sigma_L(y), \sigma_M(y)), \max(\nu_L(y), \nu_M(y)) : y \in Y\}$ .

**Definition 2.3** [8] A neutrosophic topology (briefly,  $N_s t$ ) on a non-empty set  $Y$  is a family  $\Psi_N$  of neutrosophic subsets of  $Y$  satisfying

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- (i)  $0_N, 1_N \in \Psi_N$ .
- (ii)  $L_1 \cap L_2 \in \Psi_N$  for any  $L_1, L_2 \in \Psi_N$ .
- (iii)  ${}^S L_x \in \Psi_N, \forall L_x : x \in X \subseteq \Psi_N$ .

Then  $(Y, \Psi_N)$  is called a neutrosophic topological space (briefly,  $N_s ts$ ) in  $Y$ . The  $\Psi_N$  elements are called neutrosophic open sets (briefly,  $N_s os$ ) in  $Y$ . A  $N_s s C$  is called a neutrosophic closed sets (briefly,  $N_s cs$ ) iff its complement  $C^c$  is  $N_s os$ . Definition 2.4 [8] Let  $(Y, \Psi_N)$  be  $N_s ts$  on  $Y$  and  $L$  be an  $N_s s$  on  $Y$ , then the neutrosophic interior of  $L$  (briefly,  $N_s int(L)$ ) and the neutrosophic closure of  $L$  (briefly,  $N_s cl(L)$ ) are defined as

$$N_s int(L) = \{I : I \subseteq L \text{ \& } I \text{ is a } N_s os \text{ in } Y\}$$

$$N_s cl(L) = \{I : L \subseteq I \text{ \& } I \text{ is a } N_s cs \text{ in } Y\}.$$

Definition 2.5 [1] Let  $(Y, \Psi_N)$  be  $N_s ts$  on  $Y$  and  $L$  be an  $N_s s$  on  $Y$ . Then  $L$  is said to be a neutrosophic regular open set (briefly,  $N_s ros$ ) if  $L = N_s int(N_s cl(L))$ .

The complement of a  $N_s ros$  is called a neutrosophic regular closed set (briefly,  $N_s rcs$ ) in  $Y$ .

Definition 2.6 [15] A set  $K$  is said to be a neutrosophic

- (i)  $\delta$  interior of  $G$  (briefly,  $N_s \delta int(K)$ ) is defined by  $N_s \delta int(K) = {}^S \{B : B \subseteq K \text{ \& } B \text{ is a } N_s ros \text{ in } Y\}$ .
- (ii)  $\delta$  closure of  $K$  (briefly,  $N_s \delta cl(K)$ ) is defined by  $N_s \delta cl(K) = {}^T \{A : K \subseteq A \text{ \& } A \text{ is a } N_s rcs \text{ in } Y\}$ .

Definition 2.7 [15] A set  $L$  is said to be a neutrosophic

- (i)  $\delta$ -open set (briefly,  $N_s \delta os$ ) if  $L = N_s \delta int(L)$ .
- (ii)  $\delta$ -pre open set (briefly,  $N_s \delta Pos$ ) if  $L \subseteq N_s int(N_s \delta cl(L))$ .
- (iii)  $\delta$ -semi open set (briefly,  $N_s \delta Sos$ ) if  $L \subseteq N_s cl(N_s \delta int(L))$ .
- (iv)  $e$ -open set (briefly,  $N_s eos$ ) [14] if  $L \subseteq N_s cl(N_s \delta int(L)) \cup N_s int(N_s \delta cl(L))$ .
- (v)  $e^*$ -open set (briefly,  $N_s e^* os$ ) if  $L \subseteq N_s cl(N_s int(N_s \delta cl(L)))$ .

The complement of an  $N_s \delta os$  (resp.  $N_s \delta Pos$ ,  $N_s \delta Sos$ ,  $N_s eos$  &  $N_s e^* os$ ) is called a neutrosophic  $\delta$  (resp.  $\delta$ -pre,  $\delta$ -semi,  $e$  &  $e^*$ ) closed set (briefly,  $N_s \delta cs$  (resp.  $N_s \delta PCs$ ,  $N_s \delta SCs$ ,  $N_s ecs$  &  $N_s e^* cs$ )) in  $Y$ .

Definition 2.8 [15] Let  $(X, \Psi_N)$  and  $(Y, \Phi_N)$  be any two  $N_s ts$ 's. A map  $h : (X, \Psi_N) \rightarrow (Y, \Phi_N)$  is said to be neutrosophic (resp.  $\delta$ ,  $\delta S$ ,  $\delta P$  &  $e^*$ ) continuous (briefly,  $N_s Cts$  [10] (resp.  $N_s \delta Cts$ ,  $N_s \delta SCts$ ,  $N_s \delta PCts$  &  $N_s e^* Cts$ )) if the inverse image of every  $N_s os$  in  $(Y, \Phi_N)$  is a  $N_s os$  (resp.  $N_s \delta os$ ,  $N_s \delta Sos$ ,  $N_s \delta Pos$  &  $N_s e^* os$ ) in  $(X, \Psi_N)$ .

### 3 Neutrosophic $e$ -continuous maps in $N_s ts$

Definition 3.1 A map  $h : (X, \tau_N) \rightarrow (Y, \sigma_N)$  is called neutrosophic  $e$ -continuous ( $N_s eCts$  in short) if  $h^{-1}(\lambda)$  is a  $N_s eos$  in  $(X, \tau_N)$  for every  $N_s os$   $\lambda$  in  $(Y, \sigma_N)$ .

Example 3.1  $X = \{a, b, c\} = Y$  and define  $N_s s$ 's  $X_1, X_2$  &  $X_3$  in  $X$  and  $Y_1$  in  $Y$  are

$$X_1 = hX, \left( \begin{array}{ccc|ccc|ccc} \mu a & \mu b & \mu c & \sigma a & \sigma b & \sigma c & \nu a & \nu b & \nu c \\ \hline \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} \\ \hline 0.2 & 0.3 & 0.4 & 0.5 & 0.5 & 0.5 & 0.8 & 0.7 & 0.6 \end{array} \right) i,$$

$$X_2 = hX, \left( \begin{array}{ccc|ccc|ccc} \mu a & \mu b & \mu c & \sigma a & \sigma b & \sigma c & \nu a & \nu b & \nu c \\ \hline \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} \\ \hline 0.5 & 0.9 & 0.9 & 0.6 & \mu a & \mu b & \mu c & \sigma a & \sigma b & \sigma c \\ \hline \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} \\ \hline \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} \\ \hline 0.1 & 0.1 & 0.4 & 0.5 & 0.5 & \end{array} \right) i,$$

$$X_3 = hX, \left( \begin{array}{ccc|ccc|ccc} \mu a & \mu b & \mu c & \sigma a & \sigma b & \sigma c & \nu a & \nu b & \nu c \\ \hline \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} \\ \hline -0.2 & 0.4 & 0.4 & -0.5 & 0.5 & 0.5 & -0.8 & 0.6 & 0.6 \\ \hline \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} \\ \hline 0.2 & 0.4 & 0.4 & 0.5 & 0.5 & 0.5 & 0.8 & 0.6 & 0.6 \end{array} \right) i,$$

$$Y_1 = hY, \left( \begin{array}{ccc|ccc|ccc} \mu a & \mu b & \mu c & \sigma a & \sigma b & \sigma c & \nu a & \nu b & \nu c \\ \hline \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} \\ \hline 0.2 & 0.4 & 0.4 & 0.5 & 0.5 & 0.5 & 0.8 & 0.6 & 0.6 \end{array} \right) i.$$

Then we have  $\tau_N = \{0_N, X_1, X_2, 1_N\}$  and  $\sigma_N = \{0_N, Y_1, 1_N\}$ . Let  $h : (X, \tau_N) \rightarrow (Y, \sigma_N)$  be an identity mapping, then  $h$  is  $N_s eCts$  function.

Proposition 3.1 A map  $h : (X, \tau_N) \rightarrow (Y, \sigma_N)$ , then the statements are hold but the converse does not true.

- (i) Every  $N_s \delta Cts$  is a  $N_s Cts$ .
- (ii) Every  $N_s Cts$  is a  $N_s \delta SCts$ .
- (iii) Every  $N_s Cts$  is a  $N_s \delta PCts$ .
- (iv) Every  $N_s \delta SCts$  is a  $N_s eCts$ .
- (v) Every  $N_s \delta PCts$  is a  $N_s eCts$ .
- (vi) Every  $N_s eCts$  is a  $N_s e^* Cts$ .

Proof. The proof of (i), (ii) & (iii) are studied in [15].

- (iv) Let  $\lambda$  be a  $N_s os$  in  $Y$ . Since  $h$  is  $N_s \delta SCts$ ,  $h^{-1}(\lambda)$  is a  $N_s \delta Sos$  in  $X$ . Since every  $N_s \delta os$  is a  $N_s eos$  [14],  $h^{-1}(\lambda)$  is a  $N_s eos$  in  $X$ . Hence  $h$  is a  $N_s eCts$ .
- (v) Let  $\lambda$  be a  $N_s os$  in  $Y$ . Since  $h$  is  $N_s \delta PCts$ ,  $h^{-1}(\lambda)$  is a  $N_s \delta Pos$  in  $X$ . Since every  $N_s \delta Pos$  is a  $N_s eos$  [14],  $h^{-1}(\lambda)$  is a  $N_s eos$  in  $X$ . Hence  $h$  is a  $N_s eCts$ .

(vi) Let  $\lambda$  be a  $N_sos$  in  $h$ . Since  $h$  is  $N_seCts$ ,  $h^{-1}(\lambda)$  is a  $N_seos$  in  $X$ . Since every  $N_seos$  is a  $N_se*os$  [14],  $h^{-1}(\lambda)$  is a  $N_se*os$  in  $X$ . Hence  $h$  is a  $N_se*Cts$ .

(vii) ■

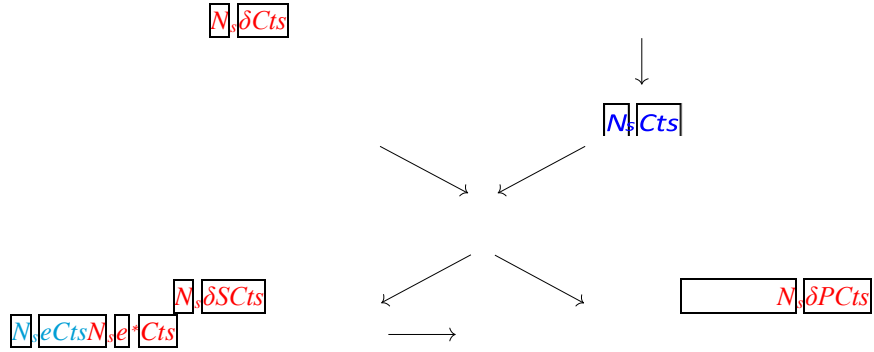


Figure 1:  $N_seCts$  maps in  $N_s ts$

Example 3.2 In Example 3.1,  $h$  is  $N_seCts$  but not  $N_s\delta PCts$ , the set  $h^{-1}(Y_1) = X_3$  is a  $N_seos$  but not  $N_s\delta P os$ .

Example 3.3  $X = \{a, b, c\} = Y$  and define  $N_s$ 's  $X_1, X_2, X_3$  &  $X_4$  in  $X$  and  $Y_1$  in  $Y$  are

$$\begin{aligned}
 X_1 &= hX, \left( \begin{matrix} \mu a & \mu b & \mu c & \sigma a & \sigma b & \sigma c & \nu a & \nu b & \nu c \\ 0.3 & 0.5 & 0.5 & 0.5 & 0.5 & 0.5 & 0.7 & 0.5 & 0.5 \end{matrix} \right), i, \\
 X_2 &= hX, \left( \begin{matrix} \mu a & \mu b & \mu c & \sigma a & \sigma b & \sigma c & \nu a & \nu b & \nu c \\ 0.5 & 0.6 & 0.8 & 0.4 & \mu a & \mu b & \mu c & \sigma a & \sigma b & \sigma c \end{matrix} \right), i, \\
 X_3 &= hX, \left( \begin{matrix} \mu a & \mu b & \mu c & \sigma a & \sigma b & \sigma c & \nu a & \nu b & \nu c \\ 0.4 & 0.5 & 0.6 & 0.5 & 0.5 & 0.5 & 0.4 & \mu a & \mu b & \mu c & \sigma a & \sigma b & \sigma c & \nu a & \nu b & \nu c \end{matrix} \right), i, \\
 X_4 &= hX, \left( \begin{matrix} \mu a & \mu b & \mu c & \sigma a & \sigma b & \sigma c & \nu a & \nu b & \nu c \\ 0.3 & 0.5 & 0.4 & 0.5 & 0.5 & 0.5 & 0.7 & 0.5 & 0.6 \end{matrix} \right), i, \\
 Y_1 &= hY, \left( \begin{matrix} \mu^a & \mu^b & \mu^c & \sigma^a & \sigma^b & \sigma^c & \nu^a & \nu^b & \nu^c \\ 0.3 & 0.5 & 0.4 & 0.5 & 0.5 & 0.5 & 0.7 & 0.5 & 0.6 \end{matrix} \right), i.
 \end{aligned}$$

Then we have  $\tau_N = \{0_N, X_1, X_2, X_3, X_1 \cap X_2, 1_N\}$  and  $\sigma_N = \{0_N, Y_1, 1_N\}$ . Let  $h : (X, \tau_N) \rightarrow (Y, \sigma_N)$  be an identity mapping, then  $h$  is  $N_seCts$  but not  $N_s\delta SCts$ , the set  $h^{-1}(Y_1) = X_4$  is a  $N_seos$  but not  $N_s\delta S os$ . Example 3.4 Let  $X = \{a, b\} = Y$  and define  $N_s$ 's  $X_1$  &  $X_2$  in  $X$  and  $Y_1$  in  $Y$  are

$$\begin{aligned}
 X_1 &= X, \mu a, \mu b, \sigma a, \sigma b, \nu a, \nu b, 0.3 \ 0.2 \ 0.5 \ 0.5 \ 0.5 \ 0.5 \\
 X_2 &= X, \mu a, \mu b, \sigma a, \sigma b, \nu a, \nu b, 0.3 \ 0.5 \ 0.5 \ 0.5 \ 0.7 \ 0.6 \\
 Y_1 &= Y, \mu a, \mu b, \sigma a, \sigma b, \nu a, \nu b, 0.3 \ 0.5 \ 0.5 \ 0.5 \ 0.7 \ 0.6
 \end{aligned}$$

Then we have  $\tau_N = \{0_N, X_1, 1_N\}$  and  $\sigma_N = \{0_N, Y_1, 1_N\}$ . Let  $h : (X, \tau_N) \rightarrow (Y, \sigma_N)$  be an identity mapping, then  $h$  is  $N_se*Cts$  but not  $N_seCts$ , the set  $h^{-1}(Y_1) = X_2$  is a  $N_se*os$  but not  $N_seos$ .

Theorem 3.1 A map  $h : (X, \tau_N) \rightarrow (Y, \sigma_N)$  is  $N_seCts$  iff the inverse image of each  $N_s cs$  in  $Y$  is  $N_s ecs$  in  $X$ .

Proof. Let  $\lambda$  be a  $N_s cs$  in  $Y$ . This implies  $\lambda^c$  is  $N_s os$  in  $Y$ . Since  $h$  is  $N_seCts$ ,  $h^{-1}(\lambda^c)$  is  $N_seos$  in  $X$ . Since  $h^{-1}(\lambda^c) = (h^{-1}(\lambda))^c$ ,  $h^{-1}(\lambda)$  is a  $N_s ecs$  in  $X$ .

Conversely, let  $\lambda$  be a  $N_s cs$  in  $Y$ . Then  $\lambda^c$  is a  $N_s os$  in  $Y$ . By hypothesis  $h^{-1}(\lambda^c)$  is  $N_seos$  in  $X$ . Since  $h^{-1}(\lambda^c) = (h^{-1}(\lambda))^c$ ,  $(h^{-1}(\lambda))^c$  is a  $N_seos$  in  $X$ . Therefore  $h^{-1}(\lambda)$  is a  $N_s ecs$  in  $X$ . Hence  $h$  is  $N_seCts$ . ■

Definition 3.2 A  $N_s t (X, \tau_N)$  is said to be a neutrosophic  $eU_{\frac{1}{2}}$  (in short  $N_seU_{\frac{1}{2}}$ )-space, if every  $N_seos$  in  $X$  is a  $N_s os$  in  $X$ .

Theorem 3.2 Let  $h : (X, \tau_N) \rightarrow (Y, \sigma_N)$  be a  $N_seCts$ , then  $h$  is a  $N_s Cts$  if  $X$  is a  $N_seU_{\frac{1}{2}}$ -space.

Proof. Let  $\lambda$  be a  $N_s os$  in  $Y$ . Then  $h^{-1}(\lambda)$  is a  $N_seos$  in  $X$ , by hypothesis. Since  $X$  is a  $N_seU_{\frac{1}{2}}$ -space,  $h^{-1}(\lambda)$  is a  $N_s os$  in  $X$ . Hence  $h$  is a  $N_s Cts$ . ■

Theorem 3.3 Let  $h : (X, \tau_N) \rightarrow (Y, \sigma_N)$  be a  $N_seCts$  map and  $g : (Y, \sigma_N) \rightarrow (Z, \rho_N)$  be a  $N_seCts$ , then  $g \circ h : (X, \tau_N) \rightarrow (Z, \rho_N)$  is a  $N_seCts$ .

Proof. Let  $\lambda$  be a  $N_seos$  in  $Z$ . Then  $g^{-1}(\lambda)$  is a  $N_s os$  in  $Y$ , by hypothesis. Since  $h$  is a  $N_seCts$  map,  $h^{-1}(g^{-1}(\lambda))$  is a  $N_seos$  in  $X$ . Hence  $g \circ h$  is a  $N_seCts$  map. ■

Remark 3.1 The composition of two  $N_seCts$  maps need not be  $N_seCts$  maps shown in following examples.

Example 3.5 Let  $X = Y = Z = \{a, b, c\}$  and define  $N_s$ 's  $X_1$  &  $X_2$  in  $X$  and  $Y_1, Y_2, Y_3$  &  $Y_4$  in  $Y$  and  $Z_1$  in  $Z$  are

$$\begin{aligned}
 X_1 &= hx, \left( \begin{matrix} \mu a & \mu b & \mu c & \sigma a & \sigma b & \sigma c & \nu a & \nu b & \nu c \\ 0.3 & 0.1 & 0.4 & 0.5 & 0.5 & 0.5 & 0.3 & 0.4 & 0.4 \end{matrix} \right), i \\
 X_2 &= hx, \left( \begin{matrix} \mu a, \mu b, \mu c, \sigma a, \sigma b, \sigma c, \nu a, \nu b, \nu c \end{matrix} \right), i, 0.3, 0.2, 0.5, 0.5, 0.5, 0.5, 0.2, 0.2, 0.4 \\
 Y_1 &= hx, \left( \begin{matrix} \mu a, \mu b, \mu c, \sigma a, \sigma b, \sigma c, \nu a, \nu b, \nu c \end{matrix} \right), i, 0.4, 0.3, 0.4, 0.5, 0.5 \\
 &\quad \begin{matrix} 0.5 & 0.4 & 0.5 & 0.5 & \mu a & \mu b & \mu c & \sigma a & \sigma b & \sigma c \\ \text{---} & \text{---} \nu a \text{---} & \text{---} \nu b \text{---} & \text{---} \nu c \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} \end{matrix} \\
 Y_2 &= hx, \left( \begin{matrix} \mu a & \mu b & \mu c & \sigma a & \sigma b & \sigma c & \nu a & \nu b & \nu c \\ 0.5 & 0.5 & 0.5 & 0.5 & 0.5 & 0.5 & 0.5 & 0.5 & 0.5 \end{matrix} \right), i \\
 Y_3 &= hx, \left( \begin{matrix} \mu a & \mu b & \mu c & \sigma a & \sigma b & \sigma c & \nu a & \nu b & \nu c \\ 0.5 & 0.5 & 0.5 & 0.5 & 0.5 & 0.4 & 0.5 & 0.5 & 0.5 \end{matrix} \right), i \\
 Y_4 &= hx, \left( \begin{matrix} \mu a & \mu b & \mu c & \sigma a & \sigma b & \sigma c & \nu a & \nu b & \nu c \\ 0.4 & 0.3 & 0.4 & 0.5 & 0.5 & 0.5 & 0.5 & 0.5 & 0.5 \end{matrix} \right), i \\
 Z_1 &= hx, \left( \begin{matrix} \mu a & \mu b & \mu c & \sigma a & \sigma b & \sigma c & \nu a & \nu b & \nu c \\ 0.3 & 0.4 & 0.4 & 0.5 & 0.5 & 0.5 & 0.4 & 0.4 & 0.5 \end{matrix} \right), i
 \end{aligned}$$

Then we have  $\tau_N = \{0_N, X_1, X_2, 1_N\}$ ,  $\sigma_N = \{0_N, Y_1, Y_2, Y_3, Y_4, 1_N\}$  and  $\rho_N = \{0_N, Z_1, 1_N\}$ . Let  $h : (X, \tau_N) \rightarrow (Y, \sigma_N)$  and  $g : (Y, \sigma_N) \rightarrow (Z, \rho_N)$  be an identity mapping, then  $h$  and  $g$  are  $N_s eCts$  function but  $g \circ h$  is not a  $N_s eCts$  functions.

**Theorem 3.4**  $h : (X, \tau_N) \rightarrow (Y, \sigma_N)$  be a  $N_s eCts$  map. Then the following conditions are hold.

- (i)  $h(N_s ecl(\lambda)) \leq N_s cl(h(\lambda))$ , for all  $N_s cs$   $\lambda$  in  $X$ .
- (ii)  $N_s ecl(h^{-1}(\mu)) \leq h^{-1}(N_s cl(\mu))$ , for all  $N_s cs$   $\mu$  in  $Y$ .

**Proof.** (i) Since  $N_s ecl(h(\lambda))$  is a  $N_s ecs$  in  $Y$  and  $h$  is  $N_s eCts$ , then  $h^{-1}(N_s ecl(h(\lambda)))$  is  $N_s ec$  in  $Y$ . Now, since  $\lambda \leq h^{-1}(N_s cl(h(\lambda)))$ ,  $N_s ecl(\lambda) \leq h^{-1}(N_s ecl(h(\lambda)))$ . Therefore,  $h(N_s ecl(\lambda)) \leq N_s cl(h(\lambda))$ .

(ii) By replacing  $\lambda$  with  $\mu$  in (i), we obtain  $h(N_s ecl(h^{-1}(\mu))) \leq N_s cl(h(h^{-1}(\mu))) \leq N_s cl(\mu)$ . Hence,  $N_s ecl(h^{-1}(\mu)) \leq h^{-1}(N_s cl(\mu))$ . ■

**Remark 3.2** If  $h$  is  $N_s eCts$ , then

- (i)  $h(N_s ecl(\lambda))$  is not necessarily equal to  $N_s cl(h(\lambda))$  where  $\lambda \in X$ .
- (ii)  $N_s ecl(h^{-1}(\mu))$  is not necessarily equal to  $h^{-1}(N_s cl(\mu))$  where  $\mu \in Y$ .

**Example 3.6** In Example 3.1,  $h$  is a  $N_s eCts$ .

- (i) Let  $\lambda = 0\mu.a2, 0\mu.b4, 0\mu.c4, 0\sigma.a5, 0\sigma.b5, 0\sigma.c5, 0\nu.a8, 0\nu.b6, 0\nu.c6$ . Then

$$\begin{aligned}
 h(N_s ecl(\lambda)) &= h \left( \begin{matrix} \mu a, \mu b, \mu c, \sigma a, \sigma b, \sigma c, \nu a, \nu b, \nu c \\ 0.2 & 0.4 & 0.4 & 0.5 & 0.5 & 0.5 & 0.8 & 0.6 & 0.6 \end{matrix} \right) \\
 &= h \left( \begin{matrix} \mu a, \mu b, \mu c, \sigma a, \sigma b, \sigma c, \nu a, \nu b, \nu c \\ 0.2 & 0.4 & 0.4 & 0.5 & 0.5 & 0.5 & 0.8 & 0.6 & 0.6 \end{matrix} \right) \\
 &= \left( \begin{matrix} \mu a, \mu b, \mu c, \sigma a, \sigma b, \sigma c, \nu a, \nu b, \nu c \\ 0.2 & 0.4 & 0.4 & 0.5 & 0.5 & 0.5 & 0.8 & 0.6 & 0.6 \end{matrix} \right)
 \end{aligned}$$

But

$$\begin{aligned}
 N_s cl(h(\lambda)) &= N_s cl \left( h \left( \begin{matrix} \mu a & \mu b & \mu c & \sigma a & \sigma b & \sigma c & \nu a & \nu b & \nu c \\ 0.2 & 0.4 & 0.4 & 0.5 & 0.5 & 0.5 & 0.8 & 0.6 & 0.6 \end{matrix} \right) \right) \\
 &= N_s cl \left( \begin{matrix} \mu a, \mu b, \mu c, \sigma a, \sigma b, \sigma c, \nu a, \nu b, \nu c \\ 0.2 & 0.4 & 0.4 & 0.5 & 0.5 & 0.5 & 0.8 & 0.6 & 0.6 \end{matrix} \right) \\
 &= h \left( \begin{matrix} \mu a & \mu b & \mu c & \sigma a & \sigma b & \sigma c & \nu a & \nu b & \nu c \\ 0.8 & 0.7 & 0.6 & 0.5 & 0.5 & 0.5 & 0.2 & 0.3 & 0.4 \end{matrix} \right)
 \end{aligned}$$

Thus  $h(N_s ecl(\lambda)) \neq N_s cl(h(\lambda))$ .

- (ii) Let  $\eta = h(0\mu.a2, 0\mu.b4, 0\mu.c4), (0\sigma.a5, 0\sigma.b5, 0\sigma.c5), (0\nu.a8, 0\nu.b6, 0\nu.c6)$ . Then

$$\begin{aligned}
 N_s ecl(h^{-1}(\eta)) &\leq N_s ecl \left( h^{-1} \left( \begin{matrix} \mu a, \mu b, \mu c, \sigma a, \sigma b, \sigma c, \nu a, \nu b, \nu c \\ 0.2 & 0.4 & 0.4 & 0.5 & 0.5 & 0.5 & 0.8 & 0.6 & 0.6 \end{matrix} \right) \right) \\
 &= N_s ecl \left( \begin{matrix} \mu a, \mu b, \mu c, \sigma a, \sigma b, \sigma c, \nu a, \nu b, \nu c \\ 0.2 & 0.4 & 0.4 & 0.5 & 0.5 & 0.5 & 0.8 & 0.6 & 0.6 \end{matrix} \right) \\
 &= h \left( \begin{matrix} \mu a & \mu b & \mu c & \sigma a & \sigma b & \sigma c & \nu a & \nu b & \nu c \\ 0.2 & 0.4 & 0.4 & 0.5 & 0.5 & 0.5 & 0.8 & 0.6 & 0.6 \end{matrix} \right)
 \end{aligned}$$

But

$$\begin{aligned}
 h^{-1}(N_scl(\eta)) &= h^{-1}(N_scl(h(\mu^a, \mu^b, \mu^c), (\sigma^a, \sigma^b, \sigma^c), (\nu^a, \nu^b, \nu^c)i)) \\
 &= h^{-1}(h(\mu^a, \mu^b, \mu^c), (\sigma^a, \sigma^b, \sigma^c), (\nu^a, \nu^b, \nu^c)i) \\
 &= h(\mu^a, \mu^b, \mu^c), (\sigma^a, \sigma^b, \sigma^c), (\nu^a, \nu^b, \nu^c)i
 \end{aligned}$$

Thus  $N_scl(h^{-1}(\eta)) = h^{-1}(N_scl(\eta))$ .

Theorem 3.5 If  $h$  is  $N_sCts$ , then  $h^{-1}(N_sint(\mu)) \leq N_sint(h^{-1}(\mu))$ , for all  $N_sos \mu$  in  $Y$ .

Proof. If  $h$  is  $N_sCts$  and  $\mu \in \sigma_N$ .  $N_sint(\mu)$  is  $N_sos$  in  $Y$  and hence,  $h^{-1}(N_sint(\mu))$  is  $N_sos$  in  $X$ . Therefore  $N_sint(h^{-1}(N_sint(\mu))) = h^{-1}(N_sint(\mu))$ . Also,  $N_sint(\mu) \leq \mu$ , implies that  $h^{-1}(N_sint(\mu)) \leq h^{-1}(\mu)$ . Therefore  $N_sint(h^{-1}(N_sint(\mu))) \leq N_sint(h^{-1}(\mu))$ . That is  $h^{-1}(N_sint(\mu)) \leq N_sint(h^{-1}(\mu))$ .

Conversely, let  $h^{-1}(N_sint(\mu)) \leq N_sint(h^{-1}(\mu))$  for all subset  $\mu$  of  $Y$ . If  $\mu$  is  $N_sos$  in  $Y$ , then  $N_sint(\mu) = \mu$ . By assumption,  $h^{-1}(N_sint(\mu)) \leq N_sint(h^{-1}(\mu))$ . Thus  $h^{-1}(\mu) \leq N_sint(h^{-1}(\mu))$ . But  $N_sint(h^{-1}(\mu)) \leq h^{-1}(\mu)$ . Therefore  $N_sint(h^{-1}(\mu)) = h^{-1}(\mu)$ . That is,  $h^{-1}(\mu)$  is  $N_sos$  in  $X$ , for all  $N_sos \mu$  in  $Y$ . Therefore  $h$  is  $N_sCts$  on  $X$ . ■

Remark 3.3 If  $h$  is  $N_sCts$ , then  $N_sint(h^{-1}(\mu))$  is not necessarily equal to  $h^{-1}(N_sint(\mu))$  where  $\mu \in Y$ .

Example 3.7 In Example 3.1,  $h$  is a  $N_sCts$ . Let  $\eta = h(0\mu.\underline{a}2, 0\mu.\underline{b}4, 0\mu.\underline{c}4), (0\sigma.\underline{a}5, 0\sigma.\underline{b}5, 0\sigma.\underline{c}5), (0\nu.\underline{a}8, 0\nu.\underline{b}6, 0\nu.\underline{c}6)i$ . Then

$$\begin{aligned}
 N_sint(h^{-1}(\eta)) &\leq N_sint(h^{-1}(h(\mu^a, \mu^b, \mu^c), (\sigma^a, \sigma^b, \sigma^c), (\nu^a, \nu^b, \nu^c)i))) \\
 &= N_sint(h(\mu^a, \mu^b, \mu^c), (\sigma^a, \sigma^b, \sigma^c), (\nu^a, \nu^b, \nu^c)i)) \\
 &= h(\mu^a, \mu^b, \mu^c), (\sigma^a, \sigma^b, \sigma^c), (\nu^a, \nu^b, \nu^c)i
 \end{aligned}$$

But

$$\begin{aligned}
 h^{-1}(N_sint(\eta)) &= h^{-1}(N_sint(\mu^a, \mu^b, \mu^c), (\sigma^a, \sigma^b, \sigma^c), (\nu^a, \nu^b, \nu^c)i)) \\
 &= h^{-1}(h(\mu^a, \mu^b, \mu^c), (\sigma^a, \sigma^b, \sigma^c), (\nu^a, \nu^b, \nu^c)i)) \\
 &= h(\mu^a, \mu^b, \mu^c), (\sigma^a, \sigma^b, \sigma^c), (\nu^a, \nu^b, \nu^c)i
 \end{aligned}$$

Thus  $N_sint(h^{-1}(\eta)) = h^{-1}(N_sint(\eta))$ .

#### 4 Neutrosophic $e$ -irresolute maps in $N_sTs$

In this section we introduce neutrosophic  $e$ -irresolute maps and study some of its characterizations.

Definition 4.1 A map  $h : (X, \tau_N) \rightarrow (Y, \sigma_N)$  is called a neutrosophic  $e$ -irresolute (briefly,  $N_sEirr$ ) map if  $h^{-1}(\lambda)$  is a  $N_seos$  in  $(X, \tau_N)$  for every  $N_seos \lambda$  of  $(Y, \sigma_N)$ .

Theorem 4.1 Let  $h : (X, \tau_N) \rightarrow (Y, \sigma_N)$  be a  $N_sEirr$ , then  $h$  is a  $N_sCts$  map. But not conversely.

Proof. Let  $h$  be a  $N_sEirr$  map. Let  $\lambda$  be any  $N_sos$  in  $Y$ . Since every  $N_sos$  is a  $N_seos$ ,  $\lambda$  is a  $N_seos$  in  $Y$ . By hypothesis  $h^{-1}(\lambda)$  is a  $N_seos$  in  $Y$ . Hence  $h$  is a  $N_sCts$  map. ■

Example 4.1 Let  $X = \{a, b, c\} = Y$  and define  $N_sS$ 's  $X_1, X_2$  &  $X_3$  in  $X$  and  $Y_1$  &  $Y_2$  in  $Y$  are

$$\begin{aligned}
 X_1 &= hX, (\mu^a, \mu^b, \mu^c), (\sigma^a, \sigma^b, \sigma^c), (\nu^a, \nu^b, \nu^c)i \\
 X_2 &= hX, (\mu^a, \mu^b, \mu^c), (\sigma^a, \sigma^b, \sigma^c), (\nu^a, \nu^b, \nu^c)i \\
 X_3 &= hX, (\mu^a, \mu^b, \mu^c), (\sigma^a, \sigma^b, \sigma^c), (\nu^a, \nu^b, \nu^c)i \\
 Y_1 &= hY, (\mu^a, \mu^b, \mu^c), (\sigma^a, \sigma^b, \sigma^c), (\nu^a, \nu^b, \nu^c)i \\
 Y_2 &= hY, (\mu^a, \mu^b, \mu^c), (\sigma^a, \sigma^b, \sigma^c), (\nu^a, \nu^b, \nu^c)i
 \end{aligned}$$

Then we have  $\tau_N = \{0_N, X_1, X_2, 1_N\}$  and  $\sigma_N = \{0_N, Y_1, 1_N\}$ . Let  $h : (X, \tau_N) \rightarrow (Y, \sigma_N)$  be an identity mapping, then  $h$  is  $N_sCts$  but not  $N_sEirr$ , the set  $Y_2$  is a  $N_seos$  in  $Y$  but  $h^{-1}(Y_2)$  is not  $N_seos$  in  $X$ .

Theorem 4.2 Let  $h : (X, \tau_N) \rightarrow (Y, \sigma_N)$  be a  $N_sEirr$ , then  $h$  is a  $N_sIrr$  map if  $X$  is a  $N_sU\frac{1}{2}$ -space.

Proof. Let  $\lambda$  be a  $N_sos$  in  $Y$ . Then  $\lambda$  is a  $N_s eos$  in  $Y$ . Therefore  $h^{-1}(\lambda)$  is a  $N_s eos$  in  $X$ , by hypothesis. Since  $X$  is a  $N_s eU_{\frac{1}{2}}$ -space,  $h^{-1}(\lambda)$  is a  $N_s os$  in  $X$ . Hence  $h$  is a  $N_s Irr$  map. ■

Theorem 4.3 Let  $h : (X, \tau_N) \rightarrow (Y, \sigma_N)$  and  $g : (Y, \sigma_N) \rightarrow (Z, \rho_N)$  be  $N_s eIrr$  maps, then  $g \circ h : (X, \tau_N) \rightarrow (Z, \rho_N)$  is a  $N_s eIrr$  map.

Proof. Let  $\lambda$  be a  $N_s eos$  in  $Z$ . Then  $g^{-1}(\lambda)$  is a  $N_s eos$  in  $Y$ . Since  $h$  is a  $N_s eIrr$  map.  $h^{-1}(g^{-1}(\lambda))$  is a  $N_s eos$  in  $X$ . Hence  $g \circ h$  is a  $N_s eIrr$  map. ■

Theorem 4.4 Let  $h : (X, \tau_N) \rightarrow (Y, \sigma_N)$  be  $N_s eIrr$  map and  $g : (Y, \sigma_N) \rightarrow (Z, \rho_N)$  be  $N_s eCts$  map, then  $g \circ h : (X, \tau_N) \rightarrow (Z, \rho_N)$  is a  $N_s eCts$  map.

Proof. Let  $\lambda$  be a  $N_s os$  in  $Z$ . Then  $g^{-1}(\lambda)$  is a  $N_s eos$  in  $Y$ . Since  $h$  is a  $N_s eIrr$ ,  $h^{-1}(g^{-1}(\lambda))$  is a  $N_s eos$  in  $X$ . Hence  $g \circ h$  is a  $N_s eCts$  map. ■

Theorem 4.5 Let  $h : (X, \tau_N) \rightarrow (Y, \sigma_N)$  be a map. Then the following conditions are equivalent if  $X$  and  $Y$  are  $N_s eU_{\frac{1}{2}}$ -spaces.

- (i)  $h$  is a  $N_s eIrr$  map.
- (ii)  $h^{-1}(\mu)$  is a  $N_s eos$  in  $X$  for each  $N_s eos$   $\mu$  in  $Y$ .
- (iii)  $N_s cl(h^{-1}(\mu)) \subseteq h^{-1}(N_s cl(\mu))$  for each  $N_s s$   $\mu$  of  $Y$ .

Proof. (i)  $\rightarrow$  (ii): Let  $\mu$  be any  $N_s eos$  in  $Y$ . Then  $\mu^c$  is a  $N_s ecs$  in  $Y$ . Since  $h$  is  $N_s eIrr$ ,  $h^{-1}(\mu^c)$  is a  $N_s ecs$  in  $X$ . But  $h^{-1}(\mu^c) = (h^{-1}(\mu))^c$ . Therefore  $h^{-1}(\mu)$  is a  $N_s eos$  in  $X$ .

(ii)  $\rightarrow$  (iii): Let  $\mu$  be any  $N_s s$  in  $Y$  and  $\mu \leq N_s cl(\mu)$ . Then  $h^{-1}(\mu) \leq h^{-1}(N_s cl(\mu))$ . Since  $N_s cl(\mu)$  is a  $N_s cs$  in  $Y$ ,  $N_s cl(\mu)$  is a  $N_s ecs$  in  $Y$ . Therefore  $(N_s cl(\mu))^c$  is a  $N_s eos$  in  $Y$ . By hypothesis,  $h^{-1}((N_s cl(\mu))^c)$  is a  $N_s eos$  in  $X$ . Since  $h^{-1}((N_s cl(\mu))^c) = (h^{-1}(N_s cl(\mu)))^c$ ,  $h^{-1}(N_s cl(\mu))$  is a  $N_s ecs$  in  $X$ . Since  $X$  is  $N_s eU_{\frac{1}{2}}$ -space,  $h^{-1}(N_s cl(\mu))$  is a  $N_s cs$  in  $X$ .

Hence  $N_s cl(h^{-1}(\mu)) \subseteq N_s cl(h^{-1}(N_s cl(\mu))) = h^{-1}(N_s cl(\mu))$ . That is  $N_s cl(h^{-1}(\mu)) \subseteq h^{-1}(N_s cl(\mu))$ .

(iii)  $\rightarrow$  (i): Let  $\mu$  be any  $N_s ecs$  in  $Y$ . Since  $Y$  is  $N_s eU_{\frac{1}{2}}$ -space,  $\mu$  is a  $N_s cs$  in  $Y$  and  $N_s cl(\mu) = \mu$ . Hence  $h^{-1}(\mu) = h^{-1}(N_s cl(\mu)) \supseteq N_s cl(h^{-1}(\mu))$ . But clearly  $h^{-1}(\mu) \subseteq N_s cl(h^{-1}(\mu))$ . Therefore  $N_s cl(h^{-1}(\mu)) = h^{-1}(\mu)$ . This implies  $h^{-1}(\mu)$  is a  $N_s cs$  and hence it is a  $N_s ecs$  in  $X$ . Thus  $h$  is a  $N_s eIrr$  map. ■

## 5 Conclusions

In this research paper using  $N_s eos$  we are defined  $N_s eCts$  map and analyzed its properties. After that we were compared already existing neutrosophic continuity maps to  $N_s e$  continuity maps. Furthermore we were extended to this maps to  $N_s e$ -irresolute maps, Finally this concepts can be extended to future research for some mathematical applications.

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